

# DMMP

## Constructing Dummy Main Methods for Android Apps with Path-sensitive Predicates

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Publicly Available at <https://github.com/cuixiaoyiyi/Leopard>

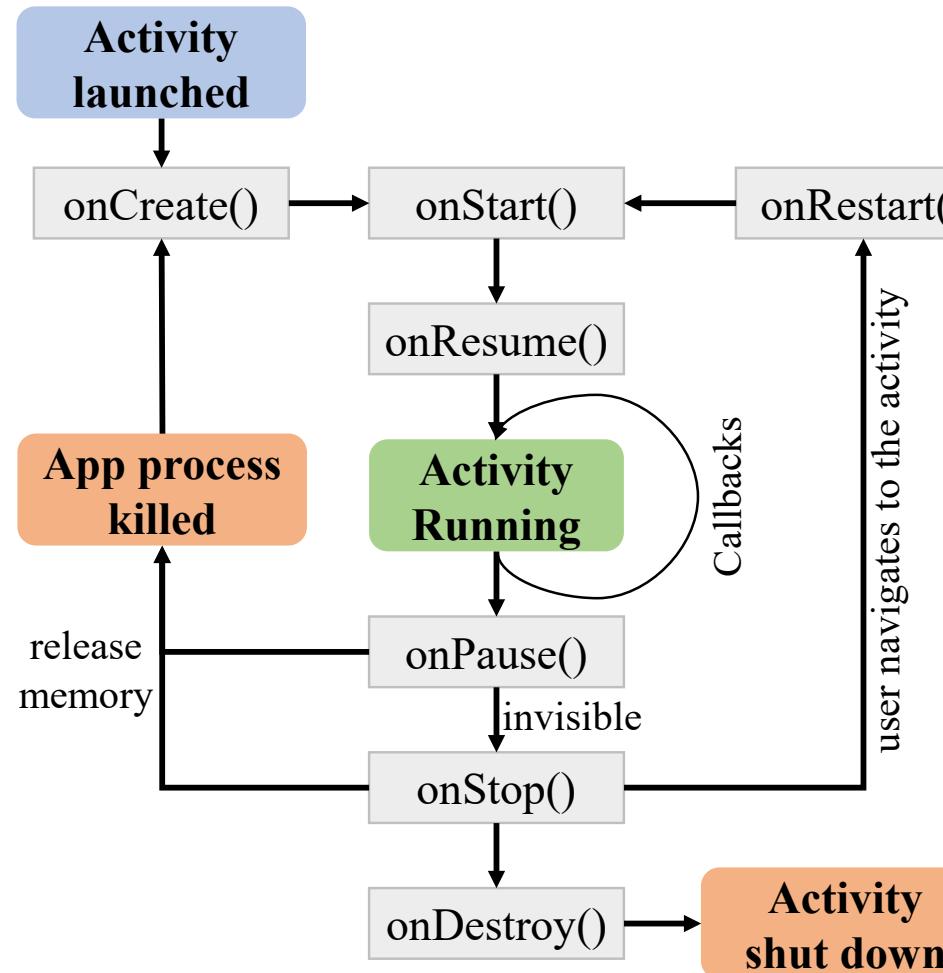
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# Background: Android Entry Method

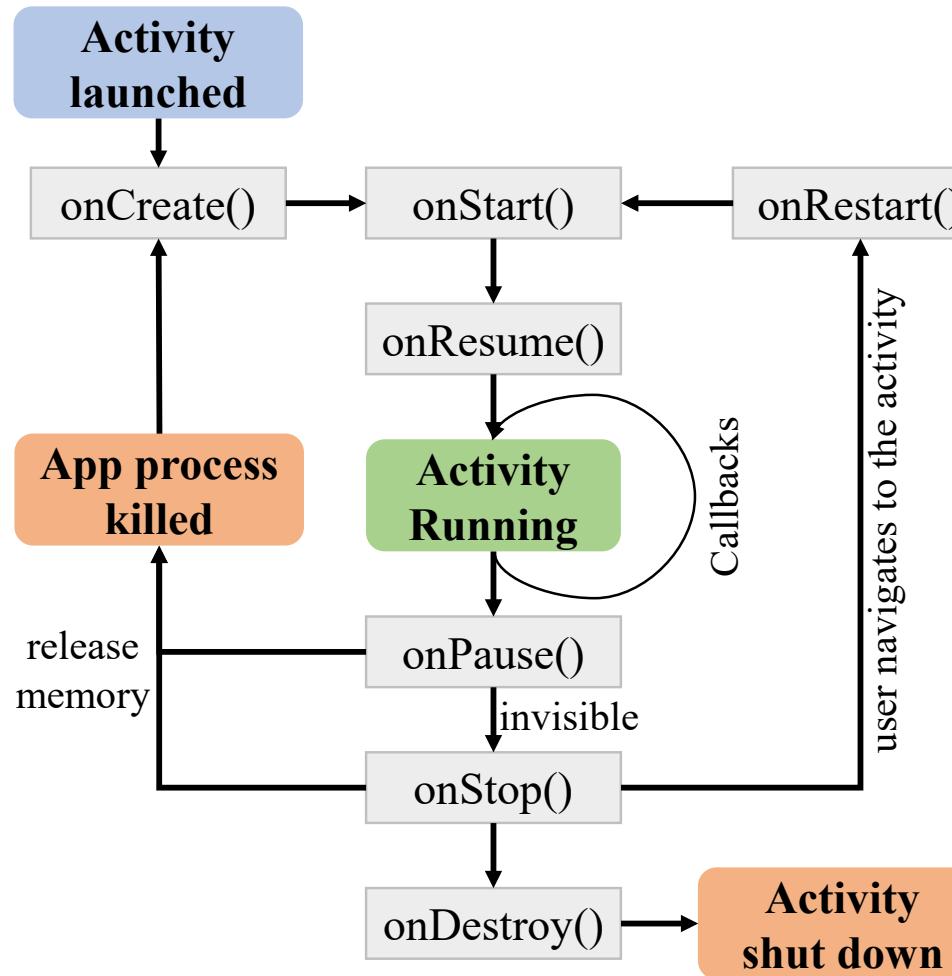
- **Android application lacks of the main method**

# Background: Dummy Main Method

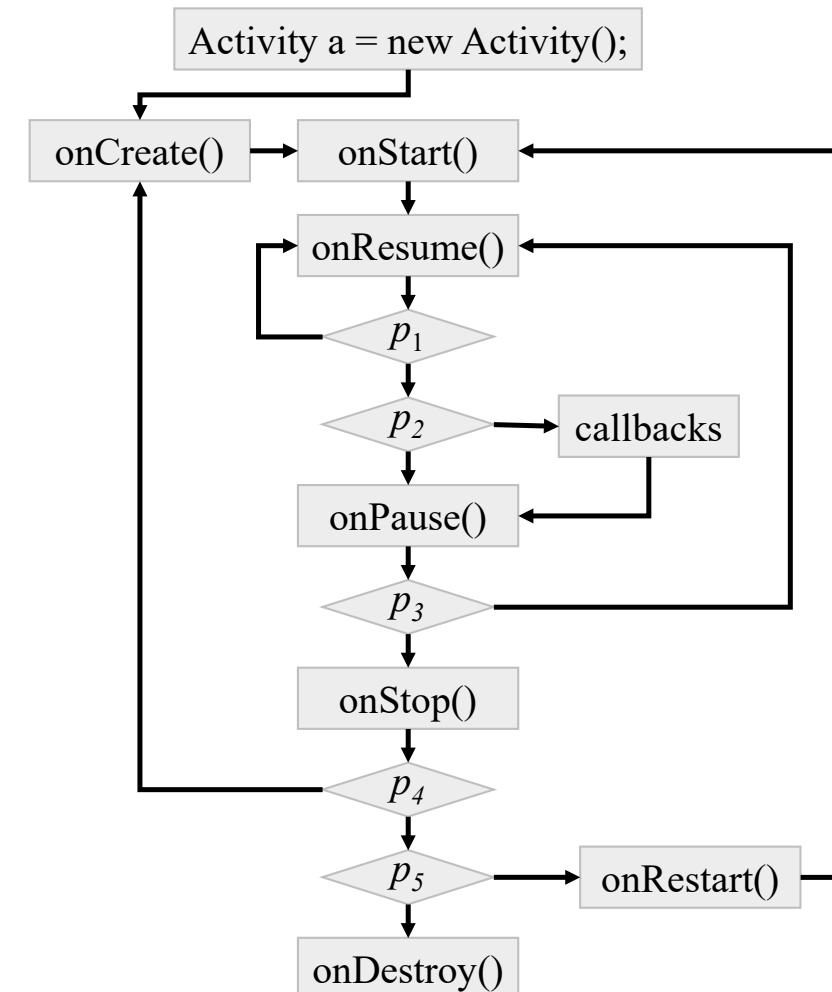


Lifecycle of Activity

# Background: Dummy Main Method



Lifecycle of Activity



Control Flow Graph of Dummy Main Method of Activity

# Background: Dummy Main Method

- The dummy main generated by FlowDroid does not consider whether the path condition is satisfied
  - path-insensitive
- However, for path-sensitive analysis, it can affect the analysis accuracy
  - false positives and false negatives.

# Motivation Example

```
// Path-insensitive Predicates modelled by FlowDroid

void dummyMain(){
    int i = 0;
    if(i == 0){ // p1 : i == 0
        onCreate(...);
        if(i == 1){ // p2 : i == 1
            if(i == 2){ // p3 : i == 2
                onResume();
            ...
        }
    }
}
```

# Motivation Example

// Path-insensitive Predicates modelled by FlowDroid

```
void dummyMain(){  
    int i = 0;  
    if(i == 0){ // p1 : i == 0  
        onCreate(...);  
        if(i == 1){ // p2 : i == 1  
            if(i == 2){ // p3 : i == 2  
                onResume();  
            ...  
        }  
    }  
}
```

- Path condition:

$$P_1(i==0) \wedge P_2(i==1) \wedge P_3(i==2)$$

Unsatisfiable



onResume(): unreachable

```
void dummyMain(){  
    int i = 0;  
    if(i == 0){ // p1 : i == 0  
        onCreate(...);  
        if(i == 1){ // p2 : i == 1  
            if(i == 2){ // p3 : i == 2  
                onResume();  
                ...  
            }  
        }  
    }  
}
```

- Path condition:

$$P_1(i==0) \wedge P_2(i==1) \wedge P_3(i==2)$$

Unsatisfiable 

onResume(): unreachable

# Motivation Example

// Path-sensitive Predicates Generated by DMMPP

```
void dummyMain(boolean[] bArr)
    if(bArr[0]) { // p1 : bArr[0]
        onCreate(...);
    if(bArr[1]) { // p2 : bArr[1]
        if(bArr[2]) { // p3 : bArr[2]
            onResume();
        ...
    }}}
```

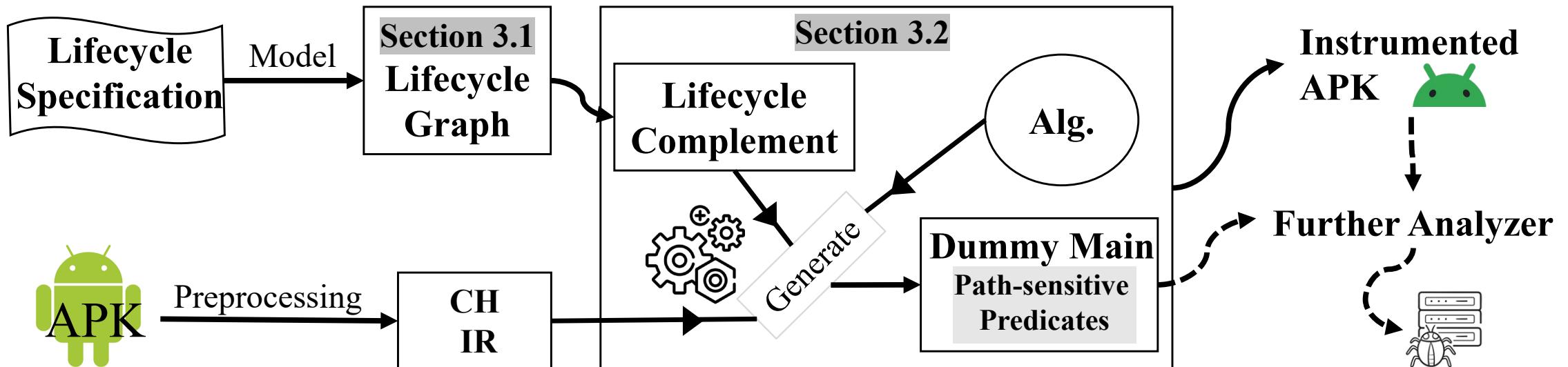
- Path condition:

$$P_1 \wedge P_2 \wedge P_3$$

Satisfiable

onResume(): reachable

# Overview of DMMPP



# Component Lifecycle Graph (CLG)

- A component lifecycle graph is a directed graph, denoted as

$$\text{CLG} = \langle N, E, T, \perp \rangle$$

- $N$  is a set of nodes and a node represents a lifecycle method, a callback list or a nop instruction
- $E$  is a set of edges
- $T$  is the start node
- $\perp$  the end node

# Lifecycle Method Complement

```
+ void onDestroy(){  
    +     super.onDestroy();  
    +}
```

# Construction

<b>Name:</b>	$A \in (a...zA...Z\$<>)^*$ $\underline{\text{name}(A)}$	<b>Type:</b>	$\underline{\text{name}(T)}$ $\underline{\text{type}(T)}$
<b>Variable:</b>	$\underline{\text{type}(T)}$ $\underline{\text{name}(V)}$ $\underline{\text{var}(T, V)}$	<b>ArrayType:</b>	$\underline{\text{type}(T)}$ $\underline{\text{arrayType}(T)}$
<b>Expression:</b>	$\underline{\text{instruction}(E)}$ $\underline{\text{instruction}(\exp(E))}$	<b>Return:</b>	$\underline{\text{instruction}(\text{returnVoid})}$
<b>Program:</b>	$\underline{\text{instruction}(I)}$ $\underline{\text{program}(P)}$ $\underline{\text{program}(I,P)}$	<b>New:</b>	$\underline{\text{type}(T)}$ $\underline{\text{instruction}(\text{new}(T))}$
<b>IfStmt:</b>	$\underline{\text{exp}(E)}$ $\underline{\text{type}(B) \text{ is boolean}}$ $\underline{\text{instruction(ifStmt}(B,E))}$	<b>Goto:</b>	$\underline{\text{exp}(E)}$ $\underline{\text{instruction(Goto}(E))}$
<b>Load:</b>	$\underline{\text{var}(Index, ARR, Ret)}$ $\underline{\text{ArrayType}(Arr)}$ $\underline{\text{type}(Index) \text{ is integer}}$ $\underline{\text{instruction(load}(Arr,Index,Ret))}$		
<b>Class:</b>	$\underline{\text{name}(Name)}$ $\underline{\text{type}(Super)}$ $\underline{\text{var}(Field)}$ $\underline{\text{fun}(Sign)}$ $\underline{\text{class}(Name,Super,Field,Sign)}$		
<b>Function:</b>	$\underline{\text{name}(Sign)}$ $\underline{\text{var}(Arg)}$ $\underline{\text{program}(Body)}$ $\underline{\text{fun}(Sign,Arg,Body)}$		
<b>Invocation:</b>	$\underline{\text{var}(Base)}$ $\underline{\text{name}(Sign)}$ $\underline{\text{var}(Arg)}$ $\underline{\text{var}(Ret)}$ $\underline{\text{instruction(call}(Base,Sign,Arg,Ret))}$		
<b>InsertExpr:</b>	$\underline{\text{exp}(E_1)}$ $\underline{\text{fun}(Sign)}$ $\underline{\text{exp}(E_2)}$ $\underline{\text{insertExpr}(Sign,E_1,[\text{after}],\text{site}(E_2))}$		

## Syntax

---

**Algorithm 1:** Dummy Main Method Generation

---

```

Input: component, clg
1 fun ← NULL, args ← ∅, body ← ∅, node ← clg.⊤, stack ← ∅;
2 caller ← NULL, map ← ∅; // map(Node, Expression)
3 stack.push(node);
4 caller ← instruction(new(type(component)));
5 // generate method invocations
6 while stack is not empty do
7   node ← stack.pop();
8   stmt ← NULL;
9   if node is ⊥ then
10     stmt ← instruction(returnVoid);
11   else if node is not ⊤ then
12     if node.m is nop instruction then
13       stmt = instruction("nop");
14     list ← getArgsFromParameters(node.m, args);
15     stmt ← instruction(call(caller, node.m, list, NULL));
16     map.put(node, call);
17     body.add(stmt);
18     map.put(node, stmt);
19     successors ← clg.successorOf(node);
20     stack.push(successors);
21 // insert if- and goto- statements
22 predicateIndex ← 0;
23 predicates ← getPredicatesFromParameters(args);
24 for node ∈ clg.N do
25   current ← map.get(node);
26   next ← body.getNext(current);
27   if node is branch node then
28     // crystal predicate
29     load(predicates, predicateIndex, predicate);
30     predicateIndex++;
31     for succ ∈ clg.successorOf(node) do
32       if next is not succ then
33         next ← succ;
34       ifStmt ← instruction(ifStmt(predicate, next));
35       insertExpr(body, ifStmt, "after", current);
36     succ ← clg.successorOf(node);
37     next ← map.get(succ);
38   if current is not ⊥ ∧ next is not NULL then
39     gotoStmt ← instruction(Goto(next));
40     insertExpr(body, gotoStmt, "after", current);
41 fun ← fun("dummyMainMethod",args,body);
42 return fun;

```

---

## Algorithm

# How to Use

## // API Invocation

```
DDMSootConfig.ANDROID_PLATFORM_PATH = $androidPlatformPath$;  
DDMSootConfig.ApkPath = $apkPath$;  
DDMSootConfig.output = $outputPath$;  
  
DDMSootConfig.sootInitialization();  
  
Set<SootClass> sootClasses = new HashSet<SootClass>(Scene.v().getApplicationClasses());  
for (SootClass sootClass : sootClasses) {  
    SootMethod sootMethod = DMMFactory.createDDM(sootClass);  
    // do your task  
}
```

# How to Use

## // Command Line

```
java -cp DMMPP.jar cn.ac.ios.dmmpp.DMMMain $androidPlatformPath$ $apkPath$ $outputPath$  
  
#output:  
$outputPath$ + "DMMPP_" + apkName
```

e.g.

```
java -cp DMMPP.jar cn.ac.ios.dmmpp.DMMMain ./android-platforms ./apks/ch.baidu.aat.apk ./output  
  
#output:  
.output/DMMPP_ch.baidu.aat.apk // as your input
```

# Evaluation: Benefits for Analyzer

App	#C	Explored Paths			Construction Time (ms)		
		FL	D	Δ	FL	D	Δ
app.fedila	6	6	12	+6	235	2960	2725
ch.bailu.a	17	17	37	+20	414	2,038	1,624
com.asdoi.	6	6	12	+6	72	2,262	2,190
com.gimran	13	13	30	+17	199	421	222
com.mobile	14	14	153	+139	1,111	516	-595
com.tuyafe	5	5	10	+5	30	1,724	1,694
com.ubersp	1	1	13	+12	40	5	-35
jp.takke.c	7	7	14	+7	42	1,932	1,890
net.gitsai	8	8	2,104	+2,096	2,775	534	-2,241
xyz.myachi	8	8	1,588	+1,580	6,991	2,377	-4,614
appnewness	7	7	35	+28	191	554	363
com.alb.pl	1	1	5	+4	12	4	-8
com.e.ulil	5	5	10	+5	32	460	428
com.pinayr	11	11	293	+282	2,094	187	-1,907
f.fajrak.b	9	9	46	+37	278	517	239
it.discors	9	9	49	+40	306	998	692
kick.wpapp	8	8	40	+32	240	486	246
kr.ieodo.a	5	5	10	+5	27	530	503
net.easyjo	7	7	14	+7	42	1,427	1,385
usd.aleavt	3	3	99	+96	459	59	-400
Total	150	150	4,574	+4,424	15,590	19,991	4,401

Totally

- Explored Paths: 29.5 times  
 $29.5 = 4,424/150$
- Time Overhead: 4.4s

Each Component

- Explored Paths: +28.5  
 $28.5 = 4,424/150-1$
- Time Overhead: 0.22s

# Cause Analysis

// Skip the complete component<sup>1</sup>

```
@Override  
protected SootMethod createDummyMainInternal() {  
    // Before-class marker  
    Stmt beforeComponentStmt = Jimple.v().newNopStmt();  
    body.getUnits().add(beforeComponentStmt);  
  
    Stmt endClassStmt = Jimple.v().newNopStmt();  
    try {  
        // We may skip the complete component  
        createIfStmt(endClassStmt);
```

```
void dummyMain(){  
    int i = 0;  
    if(i == 0){  
        return;  
    }else{  
        lifecycle methods;  
    } }
```

[1] <https://github.com/secure-software-engineering/FlowDroid/blob/develop/soot-infowflow-android/src/soot/jimple/infowflow/android/entryPointCreators/components/AbstractComponentEntryPointCreator.java#L186>

# Conclusion

- Constructing the dummy main method with path-sensitive predicates for Android application analysis
- Multiple ways for analyzers to use it
  - API invocation
  - Command line
- Benefiting the path-sensitive analyzer with a very low time overhead

# DMMPP

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